



Cretec Cybernetics



Cyberpick, More than pick.

**Global Knowledge
& Local Support**

Cyberpicker is a software intended for multi-purpose **pick & place** application, by using a **calibrated 2D camera** we can compute the **3D pose** of a particular object in the space and convert this 3D pose into any manipulator (Robot, XYZ table, ...) coordinate space.



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RECIPES EDITOR:

Easily manage your product's models and edit them with the recipes editor, allowing the user to define the grasping point and collision prevention system.



RUNTIME VIEW:

Intuitively monitor the found candidates and their robot space coordinates, it has an integrated visualizer to see the output results coded by highlighting regions and contours.



INDUSTRY 4.0:

The system is ready to go! **Supporting multiple communication standards:** TCP/IP Socket communication, MODBUS TCP, OPC UA and SQL Database connection.



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